

Optimizing Cycle Length and Green Time For A Signalized Intersection



Introduction

- Signals are the best solution for efficiently directing more than one-way traffic without relying on human presents
- It is also important to efficiently design a traffic signal

Introduction

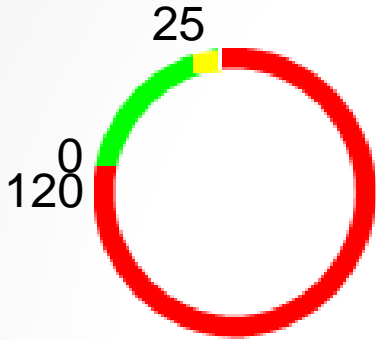
Factors involved in signal design

- Cycle length (C)
- Phase (ϕ)
- Green time (g)
- Lost time (L)

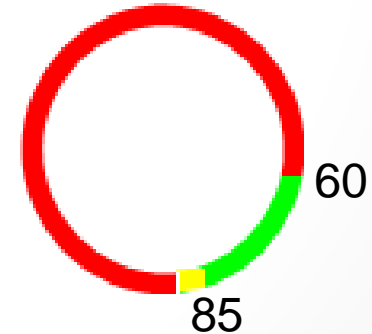
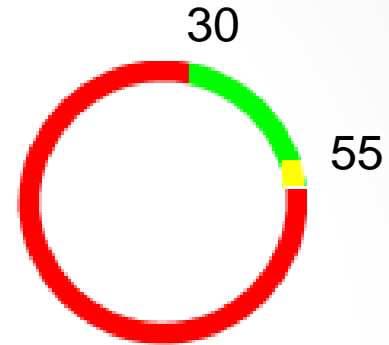
Total lost in a phase ($t_L : t_{s1} + t_{c1}$)



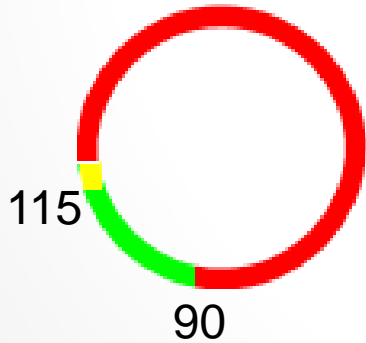
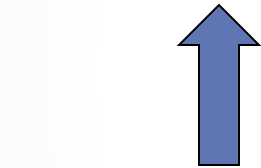
Phase 1 ($\Phi 1$): EBL+WBL
Green time: 0 to 25 sec



Phase 2 ($\Phi 2$): EBT/R+WBT/R
Green time: 30 to 55 sec



Phase 3 ($\Phi 3$): NBL+SBL
Green time: 60 to 85 sec

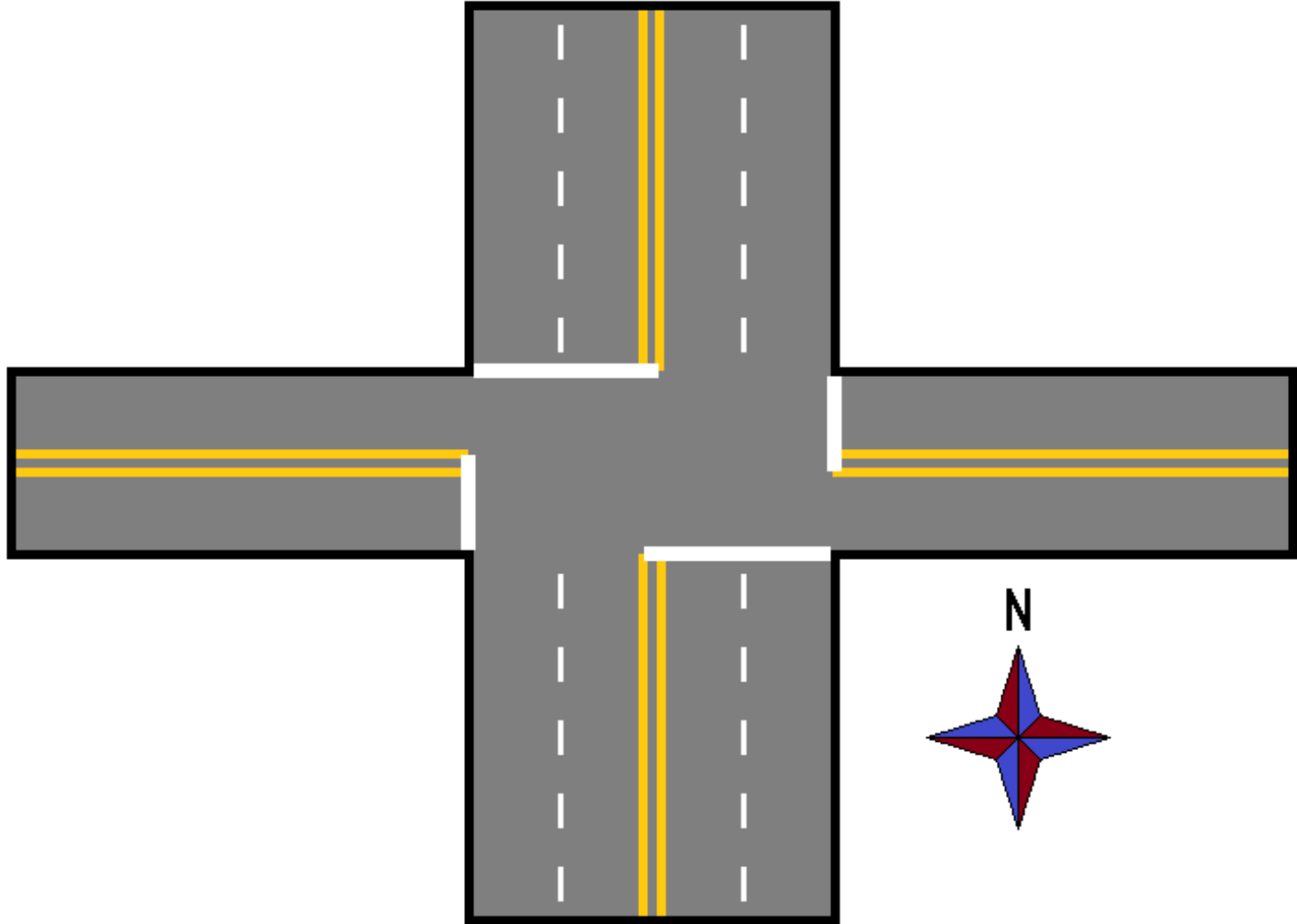


Phase 4 ($\Phi 4$): NBT/R+SBT/R
Green time: 90 to 115 sec

Introduction

Factors involved in signal design

- Saturation flow rate (s)
- Analysis flow rate (v)
- Critical lane group (v/s)



Methodology

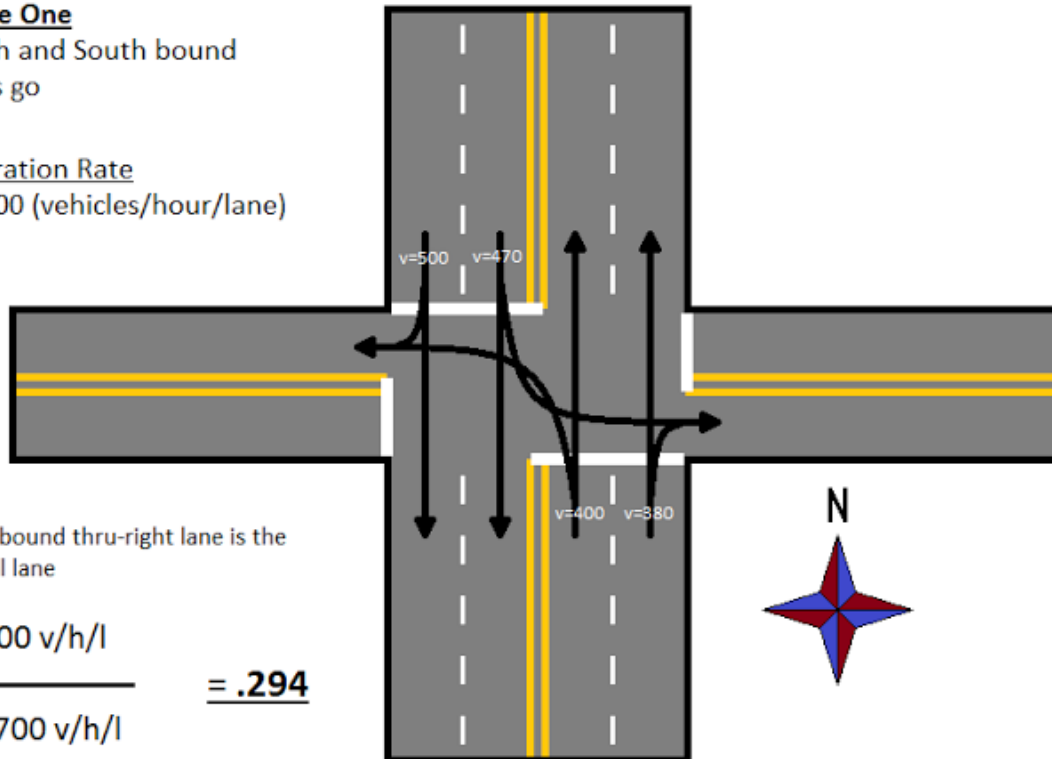
Phase 1 North-South

Phase One

North and South bound lanes go

Saturation Rate

$s=1700$ (vehicles/hour/lane)



Southbound thru-right lane is the critical lane

$v= 500$ v/h/l

$s= 1700$ v/h/l

$$\frac{v}{s} = .294$$

Methodology

Phase 1 North-South analysis and saturation flow rates

- North-bound thru and right (v)NBT/R = 380 vehicles per hour per lane (vphpl)
- North-bound thru and left (v)NBT/L = 400 vehicles per hour per lane (vphpl)
- South-bound thru and right (v)SBT/R = 500 vehicles per hour per lane (vphpl)
- South-bound thru and left (v)SBT/L = 470 vehicles per hour per lane (vphpl)
- Saturation rate for all lanes (s) = 1700 vehicles per hour per lane (vphpl)

Methodology

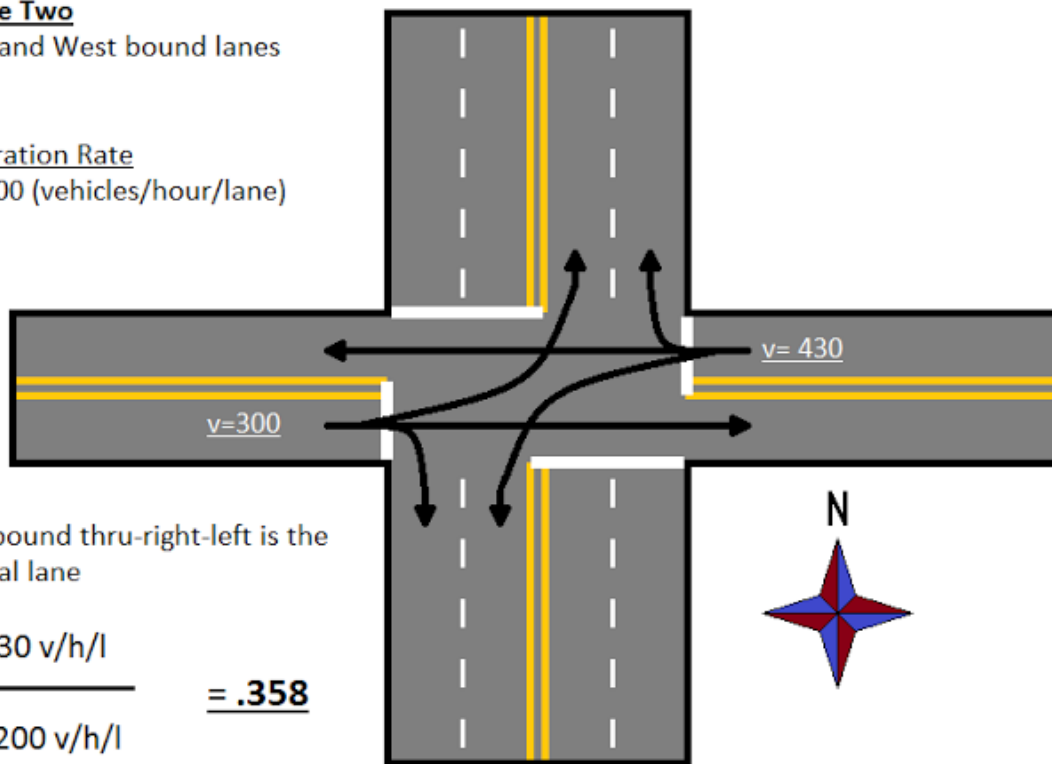
Phase 2 East-West

Phase Two

East and West bound lanes go

Saturation Rate

$s=1200$ (vehicles/hour/lane)



Eastbound thru-right-left is the critical lane

$v= 430$ v/h/l

$s= 1200$ v/h/l

$$\frac{v}{s} = .358$$

Methodology

Phase 2 East-West

- East-bound thru, right, left (v)EBT/R/L = 300 vehicles per hour per lane (vphpl)
- West-bound thru, right, left (v)WBT/R/L = 430 vehicles per hour per lane (vphpl)
- Saturation rate for all lanes (s) = 1200 vehicles per hour per lane (vphpl)

Methodology

Critical lane group determination (v/s) phase 1

$$(v/s)PHASE\ 1 = MAX \{ (v/s)NBT/R, (v/s)NBT/L, (v/s)SBT/R, (v/s)SBT/L \}$$

$$= MAX \{ (380/1700), (400/1700), (500/1700), (470/1700) \}$$

$$= MAX \{ 0.224, 0.235, 0.294, 0.2766 \}$$

= 0.294 SBT/R is the critical lane group in phase 1

Methodology

Critical lane group determination (v/s) phase 2

$$(v/s)PHASE\ 2 = MAX \{ (v/s)EBT/R/L, (v/s)WBT/R/L \}$$

$$= MAX \{ (300/1700), (430/1200) \}$$

$$= MAX \{ 0.25, 0.358 \}$$

= 0.358 WBT/R/L is the critical lane group in phase 2

Methodology

Sum of critical lane groups

- $\Sigma(v/s)C_i = (v/s)PHASE\ 1 + (v/s)PHASE\ 2$

$$= 0.294 + 0.358$$

$$= \mathbf{0.652}$$

Methodology

Optimum Cycle Length (C_{opt})

$$C_{opt} = [1.5 \times L + 5] / (1 - \Sigma(v/s)C_i)$$

$$C_{opt} = [(1.5 \times 8) + 5] / (1 - 0.652)$$

$$C_{opt} = 17 / 0.348$$

$$C_{opt} = 48.85 \text{ seconds}$$

$$C_{opt} = \mathbf{49 \text{ seconds}}$$

Methodology

Green Time Phase 1

$$g_i = ((v/s)C_i / \Sigma(v/s)C_i) \times (C - L)$$

$$= (0.294/0.652) \times (49-8)$$

$$= 18.48 \text{ seconds}$$

$$= 18 \text{ seconds}$$

Methodology

Green Time Phase 2

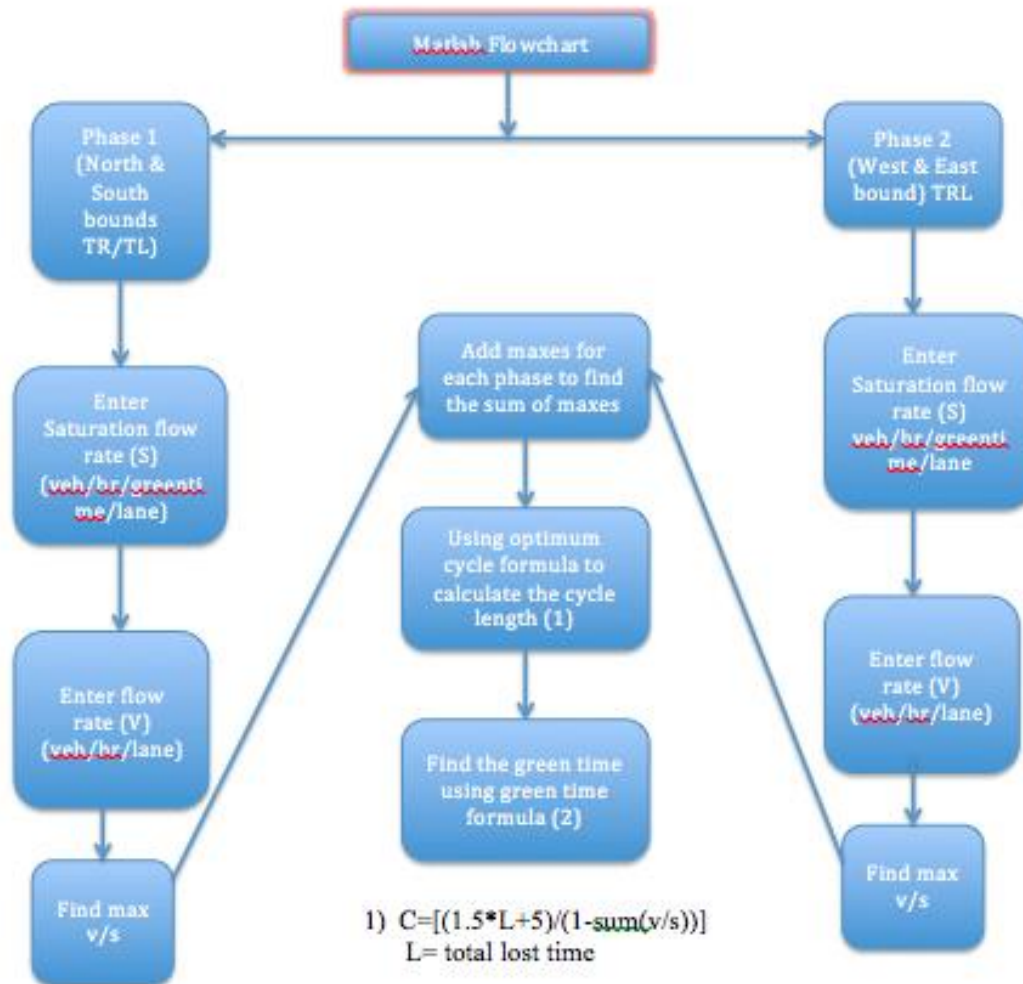
$$g_i = ((v/s)C_i / \Sigma(v/s)C_i) \times (C - L)$$

$$= (0.358/0.652) \times 49-8$$

$$= 22.52 \text{ seconds}$$

$$= \mathbf{23 \text{ seconds}}$$

Flowchart



$$1) C = \frac{1.5 * L + 5}{1 - \sum(v/s)}$$

L = total lost time

$$2) g = \frac{(v/s)}{\sum(v/s)} * (C - L)$$

Matlab script

- clear
- clc
-
- %% This program can be used to allocate green time to 2 phase a traffic signal
- % Input can be entered by a user, or in real time by road sensors
- sa=input('Input the saturation flow rate for phase a: ');
- vnr=input('Input the vehicular flow volume of northbound thru-right: ');
- vnl=input('Input the vehicular flow volume of northbound thru-left: ');
- vsr=input('input the vehicular flow volume of southbound thru-right: ');
- vsl=input('Input the vehicular flow volume of southbound thru-left: ');
- A=[vnr vnl vsr vsl]; % to find the critical lane for phase a
- vacr=max(A);
- sb=input('Input the saturation flow rate for phase b: ');
- ve=input('Input the vehicular flow volume of eastbound thru-right-left: ');
- vw=input('Input the vehicular flow volume of westbound thru-right-left: ');
- B=[ve vw]; % to find the critical lane for phase b
- vbcr=max(B);
- L=8; % total lost time is constant, but can be modified if necessary
- %% Functions are used to find the Cycle time and individual green times
- [C,cr]=cycletime(L,sa,vacr,sb,vbcr);
- ga=greenphase(L,C,cr,vacr,sa);
- gb=greenphase(L,C,cr,vbcr,sb);

Matlab function 1

- function [C,cr] = cycletime(L,sa,vacr,sb,vbcr)
- % This function finds the total cycle time
- a= vacr/sa;
- b= vbcr/sb;
- cr= a+b;
- D= 1-cr;
- N= (1.5*L)+5;
- C= N/D;
- end

Matlab function 2

- function [gi] = greenphase(L,C,cr,vi,si)
- % This function finds the green time for each phase
- $N = v_i/s_i$;
- $M = N/cr$;
- $D = C - L$;
- $g_i = M * D$;
- end

Questions ?